The kinematics of reactivation of normal faults using high resolution throw mapping

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ARTICLE INFO

Article history:
Received 16 March 2007
Received in revised form 28 April 2008
Accepted 29 April 2008
Available online xxx

Keywords:
Fault reactivation
Upward propagation
Dip linkage
Throw distribution

ABSTRACT

Normal reactivation of extensional faults offsetting Cenozoic clastic sediments is investigated using high quality 3D seismic data from offshore Brazil. These faults form complex crestal collapse grabens and result from elliptical doming of the underlying Cretaceous sequence due to Early Cenozoic uplift. The exceptional quality of this dataset allows an extremely detailed analysis of the throw distribution to be conducted on the faults. This, in addition to a reconstruction of the 3D geometry of the fault network, gives insights into the mechanisms and kinematics of reactivation. Two distinct modes of reactivation are recognised from this dataset. The main mode is a classical reactivation by upward propagation of pre-existing structures. A second mode, termed reactivation by dip linkage, is the propagation of an individual fault segment initiated above the pre-existing faults that hard link in the dip direction. For both mechanisms, reactivation processes are selective and only occur on some portions of faults. Factors controlling the preferential reactivation of some segments include: (1) orientation of the pre-existing fault plane relative to the principal stresses responsible for the reactivation, (2) segmentation of the pre-existing network and (3) maximum dimensions and throw values of pre-existing faults and basal tip line geometry associated with a detachment. Reactivation is an important process that may account for part of the scatter in fault-scaling relationships and should be included in fault-growth models.

1. Introduction

Fault propagation has been investigated with seismic data, outcrop data, and analogue and numerical modelling, yielding a number of fault-growth models (e.g. Walsh and Watters, 1988; Cowie and Scholz, 1992b; Cartwright et al., 1995). Reactivation processes have only recently been considered as an important control in fault propagation (Walsh et al., 2002; Bellahsen and Daniel, 2005). A better understanding of reactivation is essential to establish whether a fault is extinct or not (Muir Wood and Mallard, 1992), to better evaluate possible episodic fault activity (e.g. Blair and Bilodeau, 1988; Cartwright et al., 1998; Lisle and Srivastava, 2004) and to determine the effects of reactivation on fault-growth behaviour and scaling relationships (e.g. Cartwright et al., 1998; Meyer et al., 2002; Walsh et al., 2002; Nicol et al., 2005). Constraining reactivation processes has practical implications for improving the evaluation of seismic hazards (Lisle and Srivastava, 2004) and assessing the impact of reactivation on fault seal quality and fluid migration (Holdsworth et al., 1997).

Much previous work about reactivation has focused on originally extensional (e.g. Jackson, 1980; Kelly et al., 1999) or compressional (e.g. Brewer and Smythe, 1984; Enfield and Coward, 1987; Paton, 2006) fault systems that were inverted or reactivated in strike-slip mode (e.g. Kim et al., 2001). The vast majority of these studies consider faults that reactivated pre-existing basement structures, which is often seen as one of the major controls. Overall, it is still not really understood why some faults reactivate and others do not (e.g. Butler et al., 1997; Kelly et al., 1999).

This paper considers the case of a normal dip-slip system of crestal collapse faults that were subsequently affected by normal dip-slip reactivation. Additionally, the faults are not basement-rooted, so that factors controlling the reactivation are not limited to this inheritance. Using high quality 3D seismic data from offshore Brazil (Fig. 1), a detailed displacement analysis characterises the effects of reactivation on the throw distribution over the fault planes. The normal faults are interpreted to reactivate mostly by upward propagation but also by dip linkage with an overlying tier of normal faults. In addition to this behaviour, the factors influencing the selective reactivation are discussed given that not all faults are reactivated.

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Please cite this article in press as: Baudon, C., Cartwright, J., The kinematics of reactivation of normal faults using high resolution throw mapping, Struct. Geol. (2008), doi:10.1016/j.strgeol.2008.04.008
are still active and can be observed in close proximity to the occurred in the early Cenozoic in the survey area. Most diapirs anticlines suggests that folding of the Cretaceous interval occurring along contractional folds dominate within the study structures changes across the basin, but vertical salt diapirs 1993; Fiduk et al., 2004). The structural style of the salt-cored et al., 1993), and (2) a Cenozoic marine-regressive megasequence an Albian marine-transgressive megasequence with shallow prograding siliciclastic sediments derived from the erosion of coastal mountains (Chang et al., 1992). A major unconformity (Top K) separates the Mesozoic and Cenozoic megasequences (Fiduk et al., 2004).

Deformation in the Espirito Santo Basin was greatly influenced by gravity-driven salt-tectonics (Demercian et al., 1993; Fiduk et al., 2004). The structural style of the salt-cored structures changes across the basin, but vertical salt diapirs occurring along contractional folds dominate within the study area. Variation in stratatal thickness with respect to these antilines suggests that folding of the Cretaceous interval occurred in the early Cenozoic in the survey area. Most diapirs are still active and can be observed in close proximity to the present day seabed, but some became inactive during the Cenozoic. The movement of salt underlying the Cretaceous strata and the salt diapirs piercing through the Cenozoic sequence strongly influenced the location and geometry of the structures studied in this paper.

3. 3D seismic interpretation

3.1. Dataset

The BES-2 survey of 3D seismic data used in this study covers an area of c. 1600 km² within the Espirito Santo Basin in water depths ranging from c. 100 to 1800 m. The data are zero-phase migrated with 12.5 × 12.5 m inline and crossline spacing and the dominant frequency within the Cenozoic interval ranges from 35 to 60 Hz decreasing with depth. No velocity information was available for this dataset. An average velocity value of 1800 m s⁻¹ was estimated from typical seismic velocity values of clastic sediments in various slope and deep-water settings and from analogy with shallow seismic sections in other basins of the Brazilian continental margin (Rodger et al., 2006). Vertical resolution within the interval of interest is c. 7–13 m, assuming such a velocity. Seismic data beneath 4 s TWT were not available for this study but the Cenozoic is the main interval of interest for this work (Fig. 2a). Regional key horizons and fault planes were mapped at different stratigraphic levels using Schlumberger Geoframe 3.7 seismic interpretation software. Detailed measurements of the throw values on faults were made using fault normal distribution plots (T–z plot) (Cartwright et al., 1998; Baudon and Cartwright, 2008).

3.2. Seismic stratigraphic framework

A few continuous and high amplitude seismic reflections mark the base of the Cenozoic sediments. Three main units were defined from differences in seismic characteristics (Fig. 3). Unit 1 overlies directly the top Cretaceous sediments in a discordant manner and is bounded at the top by an erosional unconformity, believed to be post middle Eocene to Oligocene (E–O) in age (Fiduk et al., 2004). Unit 1 is expressed as moderate amplitude and continuous seismic reflections and is separated into 2 sub-units. Unit 1a (Top K to C60) thins above the antilines as a result of syn-tectonic deposition whereas Unit 1b (C60 to E–O boundary) forms an interval with no significant change in thickness. The basal part of Unit 2 consists, in most of the faulted areas of the survey, of a c. 100 m thick interval of chaotic seismic-facies that is interpreted as slump deposits. The base of the slump interval is expressed as an erosional truncation surface with respect to the underlying seismic reflections (Figs. 3 and 8b). The underlying strata are eroded over most of the survey and the upper tip lines of faults located in Unit 1 are truncated as a result of this erosion. Unit 2 shows a striking increase in seismic reflectivity with respect to the two surrounding units, due to a high proportion of volcani-clastic material derived from the Abrolhos Plateau (Fiduk et al., 2004). The overlying strata consist of continuous and high amplitude seismic reflections characteristic of siliclastic material of lower slope facies alternating with a few c. 50 m thick intervals of chaotic facies interpreted as slump deposits.

Unit 2 does not exhibit a significant change in thickness over the whole survey. Unit 3 overlies Unit 2 in a concordant manner and is bounded at the top by the seabed. It consists of a package of high-frequency continuous and moderate to high-amplitude seismic reflections. The overall thickness of this unit changes significantly where subsequent erosion occurred with channel complex deposition.

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Deformation of the evaporites (E) in major salt diapirs has been active since the Albian. N–S folding of the Cretaceous sequence and strata above results from early Cenozoic compression. O–P is Oligocene to Present day. A major unconformity (Top K) separates the Mesozoic and Cenozoic megasequences.

Fig. 3. 3D seismic section showing the main stratigraphic units above the Cretaceous (K) and key Cenozoic horizons. The erosional surface (E–O) at the base of Unit 2 is post middle Eocene to Oligocene in age.
4. Structural analysis and fault kinematics

4.1. General fault network

The faults in this dataset are localised in the vicinity of the recent salt diapirs and/or on the top of Cretaceous anticlines (Fig. 4). They are interpreted as typical crestal collapse structures (e.g. Bruce, 1973; McClay, 1990; Vendeville and Jackson, 1992) resulting from outer-arc stretching of the strata overlying anticlinal structures. Most faults only offset Unit 1 and do not offset the sediments above the E–O boundary at the base of Unit 2. The only faults that offset the stratigraphy above Unit 1b are located in the eastern part of the dataset and are interpreted as reactivated. The fault array affected by reactivation is characterised by a highly segmented pattern (Fig. 5).

The fault network was divided into straight segments to quantify fault strikes (Fig. 6). The rose plot displaying the strike of all faults shows two different populations (Fig. 6a). The faults located on the crest of the anticline are characterised by strike directions comprised between North and N050°/C14° with a mean value at N015°/C14°, which is very close to the direction of the axis of the anticline (N018°/C14°). The second population is more disparate with mean values striking between 120°/C14° and 130°/C14°. Rose diagrams illustrate that 43% of the faults terminate upwards at the E–O boundary and 57% are reactivated into Units 2 (Fig. 6c) and 3 (Fig. 6d). From the total length of reactivated fault segments, 79% strike in the direction of the main fault set (N to N050°). From the reactivated fault segments, c. 60% terminates downward at the top of the anticline, with c. 30% that probably detach on the limbs of the anticline (Fig. 7b). This observation indicates a close relationship between the detached faults and the occurrence of reactivation as shown by the 3D visualisation images (Fig. 7a,b) and the connection between locations of reactivated segments and isochrone 500 ms TWT of Horizon Top K (Fig. 5).

4.2. Geometry and kinematics of faults in Unit 1

The faults within Unit 1 form a graben system that tips out downwards on the crest of the anticline (Fig. 7a). Fault dimensions and displacement values decrease towards the centre of the graben system, suggesting that the faults nucleated progressively towards the centre of the crestal graben (McClay, 1990). The axial plane of the anticline strikes NE–SW and the fold axis plunges c. 2.3° toward the NE. This structure is interpreted as a semi-elliptical dome trending NE in the direction of Diapirs D1, D2 and D3 (Fig. 4). The graben system overlying this anticline in Unit 1 can be explained by elliptical doming with a small additional in plane extension when compared with the results of analogues models (Cloos, 1955, 1968; Withjack and Scheiner, 1982) or field analogue studies (Wendlandt et al., 1946; Parker and McDowell, 1951).

The kinematic history of faults offsetting Unit 1 is difficult to establish with certainty because the upper tip lines are truncated by the base of Unit 2. In addition, small growth faults with relatively regular and low displacement gradients can be very similar to faults that propagated blindly (Petersen et al., 1992; Baudon and Cartwright, 2008), further complicating the interpretation. The onset of faulting within Unit 1 occurred between the Early Cenozoic (formation of major anticlines) and the Late Eocene (E–O erosional surface). Subtle growth packages in close proximity to the fault planes in the upper part of Unit 1b (Fig. 8a) are associated with steep positive gradients on the throw profiles (i.e. profile 6 in Fig. 13). These indications of syn-sedimentary movement suggest that, regardless of the early kinematic evolution

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4.3. Fault network in Units 2 and 3

Faults offsetting Units 2 and 3 predominantly strike between N and N050° (Fig. 5b). The fault planes are generally increasingly planar and steepen in the upper part. These portions of reactivated fault planes are interpreted to have propagated by blind propagation on the basis of the following criteria: (1) upper tip-lines plunge towards the lateral tips for individual faults, (2) faults terminating upward at different stratigraphic levels (Childs et al., 2003; Baudon and Cartwright, 2008), (3) absence of stratigraphic thickening in the hanging wall or evidence of scarp, and (4) upper-tip folding in a monocline style as expected ahead of propagating blind faults (e.g. Gawthorpe et al., 1997). In addition to these observations, the characteristics of throw distribution on these upper portions of reactivated faults are typical for the range of upper-tip gradients of blind faults (Fig. 10b). All these criteria strongly suggest that the faults grew by blind propagation above the E–O boundary, so that sediments of Unit 2 and most of Unit 3 were deposited before the second period of deformation.

The kinematic history proposed for the crestal-collapse faults can be summarised in a three-step model, illustrating two distinct phases of faulting separated by a period of quiescence (Fig. 9).

5. Characteristics of reactivation

5.1. Throw distribution analysis on faults

Representative vertical throw-distribution plots for the faults located in the reactivated area were grouped into two main populations. The first group includes profiles of non-reactivated faults that terminate upward at the E–O boundary (Fig. 10a) and the second group contains reactivated faults terminating within Units 2 or 3 (Fig. 10b).

5.1.1. Non-reactivated eroded faults

The vertical throw distribution on faults that only offset Unit 1 are truncated in the upper portion where throw values of the shallowest measurable offset horizon range from c. 5 to 20 m...
These correspond to fault segments eroded by the slump horizons identified on seismic sections (Fig. 8b). The vertical throw-distribution plots are mostly characterised by M-type or C-type throw-profiles. The intervals with maximum throw values (up to c. 25 m) are located dominantly within Unit 1b, between Horizons C50 and C60. Maximum throw-values for faults that tip out downwards without detachment are located within Unit 1b whereas faults that detach generally exhibit throw maxima in Unit 1a.

5.1.2. Reactivated faults

Most faults that terminate upward in Units 2 and 3, and are hence interpreted as reactivated, exhibit stepped vertical throw-profiles, which can be typically separated into two parts (Fig. 10b). The lower part has a similar shape to the T–z plot for non-reactivated faults. Although the shapes are comparable, the magnitude of the throw values is systematically greater for the reactivated faults compared to the non-reactivated faults with average maximum throw values of c. 45 m. The central and upper parts of the T–z profiles (i.e. above the E–O boundary to the upper tip) are generally characterised by almost constant positive throw gradients per individual faults, whose values range from 0.01 to 0.07 (e.g. profiles 6, 7 and 8). Less commonly, there is a change of throw gradient within Unit 2 and Unit 3 (e.g. profile 5).

All reactivated faults exhibit an abrupt step in throw profiles at the E–O boundary. These steps are interpreted as characteristic of reactivation, and are not attributed to lithological effects during fault propagation through mechanical barriers (e.g. Gross et al., 1997; Wilkins and Gross, 2002). Contrasts in acoustic impedance of the sediments above and beneath this boundary are not sufficient to infer a major change in the mechanical properties. The reduction in fault throw above the E–O boundary is too large to be attributed only to a weak layer. Also, increase of throw gradients just beneath the boundary (i.e. profile 9) is attributed to the growth packages at the remnant upper tip regions of faults truncated at this boundary, indicating that the
The vast majority of the reactivated faults grew by upward propagation from the parent fault and many only had specific portions of the parent fault surface reactivated (Figs. 5 and 11). For the example illustrated in Fig. 11, the central region of the parent fault was not reactivated. This central portion is delimited by branch lines with intersecting faults, and a close spatial association exists between the original segmentation of the parent fault and the subsequent selective reactivation.

The upward propagation mode of reactivation can be recognised in the throw distribution on the reactivated fault (Fig. 11b). The upper tip line varies laterally in position from 2400 ms TWT at the lateral regions to 3000 ms TWT in the central portion of the fault. The basal tip line is located at c. 3800 ms TWT at the SSW and the central regions (lines 1–6) and terminates at progressively shallower levels up to 3550 ms TWT at the NNE lateral tip. The seismic data show the fault detaching on the limb of the underlying anticline between lines 1 and 6 whereas in contrast the lower tip line abuts against an antithetic fault between lines 7 and 11. Regions of maximum throw values are located between 3000 and 3800 ms TWT. More specifically, the contours are centred on two maxima situated between 3700 and 3800 ms TWT on those portions of the fault plane that detach at the base. Above the E–O boundary the contours are more widely spaced and sub-horizontal with no sign of perturbation or local maxima.

$T$–$z$ plots for the central portion of the fault plane ($T$–$z$ plots 4, 5 and 6) are characterised by typical profiles of non-reactivated faults (Fig. 10a). Throw maxima are located in the lower part of the profile between C60 and Top Cretaceous horizons as expected for detaching faults. The $T$–$z$ plots obtained for the portions of faults that are interpreted as reactivated ($T$–$z$ plots 1, 2, 3, 7, 8, 9, 10 and 11) exhibit typical stepped profiles with a major break in throw gradients corresponding with the E–O boundary. Upper parts of the profiles overlying the E–O boundary are generally characterised by a constant positive throw gradient between c. 0.01 and 0.06 (such as $T$–$z$ plots 7, 9 and 10). Alternatively, some profiles exhibit a near zero gradient between the E–O boundary and Horizon C30 (such as $T$–$z$ plots 1, 2 and 11). However, C-type profiles are absent in the upper parts of these $T$–$z$ plots or lack significant irregularities in the throw gradients.

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5.2.2. Reactivation by dip linkage

Dip linkage is a much less common mode of reactivation (c. 5% of reactivated faults in this dataset), but is nonetheless interesting and with potentially wider implications for reactivation in fault systems where strong mechanical layer anisotropy favours localisation of new faults in different mechanical ‘tiers’. An example of reactivation by dip linkage is presented in this section (Figs. 7c, 12 and 13). Segments A and B are pre-existing faults offsetting Unit 1 and Segment R is a fault that initiated individually within Units 2 or 3 above Segments A and B and strikes in a similar direction (Fig. 7c). A map view of Horizon C50 with 3 seismic sections taken along strike illustrates the spatial relationship between these faults (Fig. 12a). In the northern part of the fault, Segment A is reactivated by dip linkage with Segment R (Fig. 12b). In the region of northern branch line ($x$–$x'$), Segment R is separated from Segment A by a relay zone at the E–O boundary (Fig. 12c). Further south, Segment R switches toward the west to link with Segment B, which is reactivated, leaving Segment A truncated at the E–O boundary (Fig. 12d). At the southern branch line ($y$–$y'$) between Segments A and B, Segment R switches back to reactivate a dip link to Segment A. One condition for facilitating reactivation by dip linkage is the similarity between the dips and strikes of the segments nucleating in the upper units and the parental segments beneath. In addition to this similarity, segmentation of the pre-existing network is clearly controlling the location for selective reactivation (Fig. 5).

The throw distribution of the reactivated fault provides additional evidence for the dip-linkage interpretation (Fig. 13b). Toward the SSW the upper tip-line of the fault terminates between 2300 and 2400 ms TWT but is deeper at c. 3000 ms TWT in the central portion where Segment A is not reactivated. Two principal throw maxima are located between 3000 and 3400 ms TWT. The throw contours above the E–O boundary are irregular but crudely centred on small individual zones of maximum throw values such as between 2800 and
3000 ms TWT in the vicinity of line 3. This throw maximum is separated from the lower part of the fault plane by a horizontal zone of throw minima located in the vicinity of the E–O boundary at c. 3000 ms TWT.

Vertical throw distribution plots also show subtle details of reactivation by dip linkage (Fig. 13c). T–z plots obtained on Fault A where it overlaps with Segment B (T–z plot 4) is characterised by a profile typical of non-reactivated faults (Fig. 10a). Elsewhere, throw profiles have two parts separated by a sharp change in throw values and gradients as is expected for reactivated faults (Fig. 10b). The upper part of these profiles above the E–O unconformity does not always have single positive gradients. T–z plots 1, 2, 3, 6 and 7 are characterised by throw profiles resembling C-type patterns (cf. Baudon and Cartwright, 2008) between the upper-tip point and Horizon C20. Throw profiles 3 and 5 exhibit a C-type vertical throw-distribution plot between C30 and the E–O boundary. This difference is interpreted as being the consequence of reactivation by dip linkage of individual Segment R. The zone of linkage between two originally individual segments that are hard linked is recognisable by a zone of throw minima and steepening of the throw gradients (e.g. Peacock and Sanderson, 1994; Cartwright et al., 1995). This segment initiated within the upper part and propagated downward to link with the upper tip line of pre-existing Fault A.

Faults that are reactivated by the dip-linkage process are characterised by stepped profiles with a major break in throw gradients and possible zones of separated C-shape profiles above the E–O boundary. This type of reactivation is recognisable by throw maxima in the upper part of the fault plane separated from the pre-existing parts by throw minima.

6. Discussion

6.1. Modes of reactivation

Reactivated structures have previously been described as growing by further propagation of the pre-existing structure after a significant period of quiescence (e.g. Holdsworth et al., 1997; Nicol et al., 2005). The classical model for reactivation is described as upward propagation from pre-existing structure as faults are generally generated at depth and grow upward (Richard and Krantz, 1991). This study has identified two distinct modes of reactivation for the crestal extensional faults, upward propagation and dip linkage. Both modes of reactivation are recognised by typical stepped profiles with a major break in throw gradients corresponding to the E–O boundary. Subtle differences in the throw distribution provide insights into the recognition of either mode. Upward propagation is characterised by profiles exhibiting a regular decrease in throw values and gradients up to the upper tip point (Fig. 11), whereas reactivation by dip linkage can be identified by throw maxima in the upper part of the fault plane separated from the pre-existing parts by throw minima (Fig. 13). Further growth of the two hard-linked segments after reactivation might attenuate the throw variations and obscure the differentiation of these two types of reactivation.

6.2. Preferential reactivation

6.2.1. Direction of reactivation extension

The probability of reactivation is directly related to the orientation of the fault planes relative to the principal stresses and their ability to accommodate the imposed strains (White et al., 1986; Richard and Krantz, 1991), as well as difference in friction coefficients and cohesion (Sibson, 1985).

Evaluating the direction of extension during reactivation is difficult. However, the faults interpreted as reactivated from the 3D seismic data mostly strike in a NNE–SSW direction, especially the
Fig. 10. Vertical throw–distribution plots. Each $T$–$z$ plot represents the throw values plotted against the time in ms TWT. (a) Faults that are eroded by the E–O surface and are not reactivated are characterised by truncated throw profiles. (b) $T$–$z$ plots for reactivated faults. C50 and C60 are key horizons, the wavy line indicates the location of E–O erosional surface and Unit 2 is represented by the shaded area.

Fig. 11. (a) Schematic illustration of the 3D geometry of a typical example of a fault that reactivated by upward propagation (indicated by the arrows). The central portion that is not reactivated is delimited by dip-parallel branch lines of interacting faults (dashed lines). (b) Throw contour plot showing lines of equal throw value spaced every 10 ms TWT and up to 70 ms TWT (dark colour). Dotted lines indicate the areas of reactivation. (c) Vertical throw distribution plot for a reactivated fault by upward propagation. Each $T$–$z$ plot shows the throw values ($T$) up to 80–ms TWT against the time in ms TWT. Wavy lines represent the E–O boundary.

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faults that tip out in Unit 3 (Fig. 6). The dominant trend of reactivated faults suggests that the orientation of the pre-existing fault planes with respect to the direction of the principal stress axis characterising the second phase of deformation is an important factor influencing preferential reactivation. In addition to this relationship, comparison of the fault network with analogue modelling and field studies suggests that this geometry is due to a WNW–ESE extension, which is concordant with the orientation of the Cretaceous anticlinal axis (N018°/C14°). This direction also corresponds to the orientation of the second and smaller population of faults striking between N120°/C14° and N130°/C14°.

This interpretation suggests that the selection for reactivation is strongly influenced by the orientation of the faults with respect to the principal stress axes of the phase of deformation resulting in reactivation. However, no quantitative conclusion can be drawn in the absence of further information on the direction of the second extensional phase.

6.2.2. Selective reactivation influenced by segmentation

The crestal-collapse faults from the Espirito Santo Basin are interpreted to be reactivated depending on their orientation. However, it is also observed that faults do not always reactivate along the entirety of their length. Particular portions or segments of faults are preferentially reactivated although several non-reactivated segments strike in a similar direction as the reactivated segments (Fig. 5). Therefore, the reactivation must be influenced by factors other than the faults orientation.

This study proposes that preferential reactivation is also related to fault segmentation or connectivity as previously suggested (Kelly et al., 1999). The portions of major faults that are reactivated are often delimited by intersections with other fault segments (Fig. 5). The horizontal limits of reactivation often correspond to overlapping zones with other interacting faults and zones of linkages through the branch lines on the fault planes (Figs. 5, 11 and 13). It must be noted that 5–10% of reactivated portions are not delimited by branch line or interaction with another structure that is observable at seismic scale (Fig. 5).

6.2.3. Influence of the dimensions of faults and basal tip geometry on selective reactivation

Preferential reactivation has been attributed to larger faults partly due to the weaker friction associated with their smooth fault plane (Scott et al., 1994) and an abundance of fluid circulation in large fault networks (Kelly et al., 1999). It was suggested that in some cases smaller faults offsetting the cover do not reactivate as opposed to some larger basement faults, which are not factors for

Fig. 12. Example of reactivation by dip linkage. (a) Map view of fault geometry with location of the seismic-sections shown in (b)–(e). Location of this fault is indicated by the rectangle in Fig. 5a–d. Seismic sections along strike of the structure. Dashed line is the E–O boundary: (b) Segment A is reactivated, (c) Segment R is separated from the lower-tier faults, (d) Segment R dip link with Segment B, Segment A is not reactivated anymore, (e) Segment R switches back to reactivate Segment A.
these faults in the Espirito Santo Basin because they are all small and offset the cover.

The magnitude of the throw values is greater for the reactivated faults compared to the non-reactivated faults (Fig. 10). The question remains whether these portions that were reactivated because of their great throw values are representative of mechanically more efficient slip locations or if they gained great throw values only through reactivation. Comparison of reactivated with non-reactivated portions of faults illustrating reactivation by upward propagation (Fig. 11) and dip linkage (Fig. 13) provides insight into this issue. In the case of upward propagation, the SSW reactivated segments exhibit larger throw values than either the non-reactivated central part or the NNE reactivated segment. Interestingly, the SSW reactivated segment detaches on the limb of the anticline. This observation perhaps suggests that other controls such as the geometry of the basal tip region affect the selection of reactivated portions. In the dip linkage example, Segment R linked to Segment B although overlapping Segment A is characterised by greater throw values. In this case, the orientation of the upper-tier fault with respect to the faults located in Unit 1 is clearly a dominant factor on selective reactivation rather than the dimension or maximum throw values.

The possibility that the occurrence of reactivated fault segments is linked to the basal-tip geometry with respect to the anticline is further supported by more general mapped relationships in the study area. Of the total cumulative length of reactivated fault segments, along 60% of this length, the segments are observed to terminate downward into the flanks of the anticline and detach on the limbs of the anticline (Figs. 7b and 8). One interesting observation regarding the basal-tip geometry is that faults that tip out downward without detachment exhibit throw maxima within Unit 1b whereas faults that detach on the anticline flanks generally exhibit throw maxima in Unit 1a (Fig. 13). Detached faults have larger throw values than non-detached faults, so the characteristics of fault basal-tip regarding the anticline are correlated with the throw magnitude. It is therefore proposed that the basal tip

![Figure 13](image-url)
6.3. Implications

As previously suggested in earlier papers on fault growth (e.g. Walsh et al., 2002; Vetel et al., 2005), a reactivated structure can exhibit an anomalously low displacement-to-length ratio (D/L). The length of faults is generally established during the phase of faulting that created the pre-existing faults. When the faults are reactivated, a disproportionate increase of maximum displacement relative to length shifts the growth path in a plot of displacement versus length to a path with higher D/L ratio. In the case of the Espirito Santo basin faults, the length was established during faulting phase 1. The reactivated faults resulting from faulting phase 2 accumulated twice the amount of displacement whilst maintaining near constant fault trace length. It is therefore necessary to consider reactivation as an important factor for scatter in D/L ratio as these scaling relationships are used to promote several fault growth models (e.g. Walsh and Watters, 1988; Cowie and Scholz, 1992a; Cartwright et al., 1995). Models of fault evolution of this type also provide insights into the timing of fault activity which has a direct application to hydrocarbon migration and sealing of faults in petroleum reservoirs (McClay, 1990). For example, accurate timing of any reactivation phases with reference to constraints on the filling of hydrocarbon traps would be critical for an evaluation of seal risk (Cartwright et al., 2007). Traps are much more likely to leak during periods of fault reactivation than during periods when the faults are inactive, all other parameters of seal integrity being the same (Hooper, 1991; Gartrell et al., 2002; Cartwright et al., 2007). A further understanding of reactivation processes will greatly improve petroleum prediction of seal integrity, trap geometry and fluid circulation or migration. The different modes of reactivation discussed here may also be relevant for consideration of reactivation potential of seismogenic basement faults in that structural context and the geometry of deeper detachments may be a significant factor in priming a given segment for later reactivation (Sibson, 1981; Hickman et al., 1995).

7. Conclusions

This paper investigated the kinematics of small crestal collapse faults offsetting Cenozoic clastic sediments that overlie Cretaceous anticlines using high quality 3D seismic data from offshore Brazil. Geometrical, kinematic and stratigraphic evidence were presented to demonstrate the occurrence of reactivated faults in the study area. (1) A large percentage of the fault network terminates upward at the E–O erosional surface located at the base of Unit 2. (2) The faults were active at the free surface at the time of deposition of the sediments that form the upper part of Unit 1b. (3) Fault segments offsetting Units 2 and 3 grew entirely by blind propagation. The second phase of faulting is post-sedimentary and therefore implies a period of quiescence while deposition of Units 2 and 3. (4) An abrupt step in the vertical throw distribution (T=2 plots) marks the zone of newly propagating portions of faults.

Two different modes of reactivation are recognised. The main mode is a classical reactivation by upward propagation of pre-existing structures. The second mode, which is termed reactivation by dip linkage, involves the propagation of an individual fault initiated within the upper Units 2 and 3 during the second phase of faulting. Further propagation of these faults result in hard linkage in the dip direction with pre-existing faults. Throw profiles and contour plots exhibit a regular decrease in throw values and gradients up to the upper tip for reactivated faults by upward propagation. Throw minima separate the upper parts from the pre-existing fault in the case of reactivation by dip linkage. For both modes, reactivation processes are selective and only occur on portions of some faults. The factors that control or influence the preferential reactivation of some portions amongst others are: (i) preferential orientation of the pre-existing faults at 90–110° relative to the estimated principal stresses results in faulting phase 1, (ii) segmentation of the pre-existing network, (iii) maximum dimensions and throw values of pre-existing faults, and (iv) basal tip-line geometry associated with a detachment.

Acknowledgements

We wish to thank the Compagnie Générale de Géophysique for supplying the seismic data and permission to publish this work. Schlumberger Ltd is acknowledged for providing Geoquest seismic interpretation software. This paper has benefited from discussions with Richard Davies, Richard Lisle and Simon Higgins. Two anonymous reviewers and Editor William M Dunne are thanked for thoughtful and constructive reviews which greatly improved the manuscript.

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